

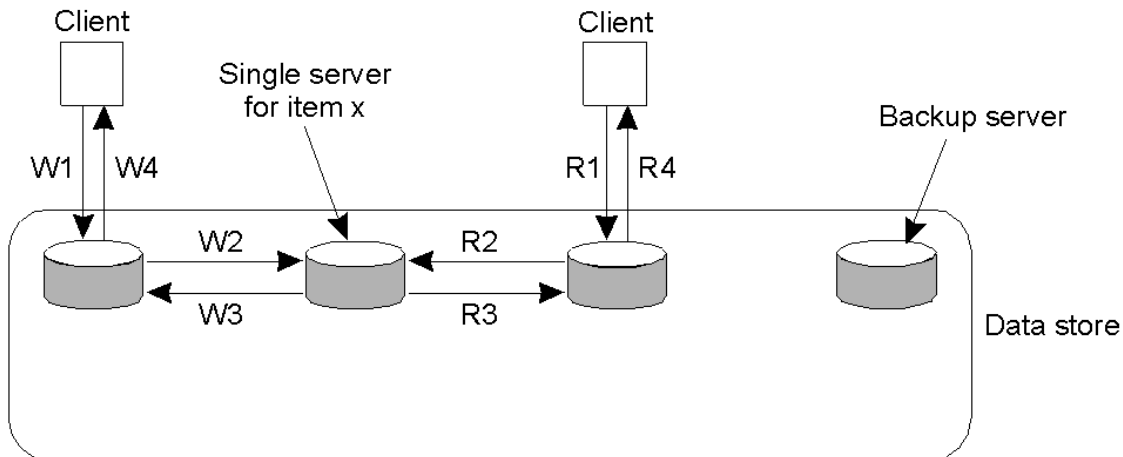
Replication

- Part 1: Remote write and local write protocols
- Part 2: Quorum-based protocols

Implementation Issues

- Two techniques to implement consistency models
 - Primary-based protocols
 - Assume a primary replica for each data item
 - Primary responsible for coordinating all writes
 - Replicated write protocols
 - No primary is assumed for a data item
 - Writes can take place at any replica

Remote-Write Protocols

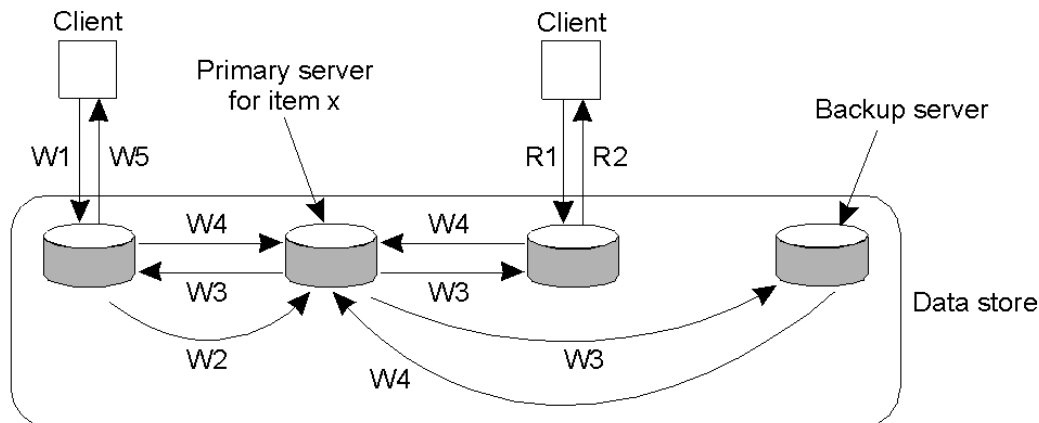


W1. Write request
 W2. Forward request to server for x
 W3. Acknowledge write completed
 W4. Acknowledge write completed

R1. Read request
 R2. Forward request to server for x
 R3. Return response
 R4. Return response

- Traditionally used in client-server systems (no replication)

Remote-Write Protocols (2)

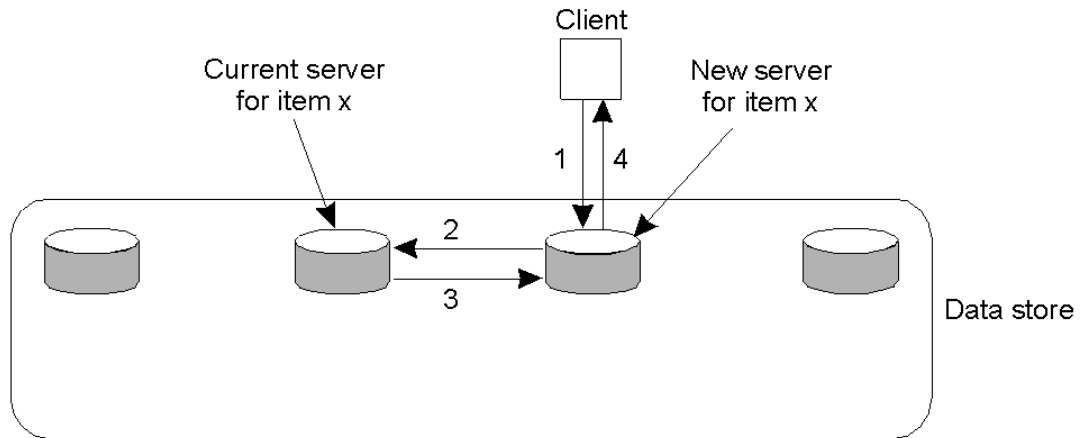


W1. Write request
 W2. Forward request to primary
 W3. Tell backups to update
 W4. Acknowledge update
 W5. Acknowledge write completed

R1. Read request
 R2. Response to read

- Primary-backup protocol (1 prim, 3backup)
 - Allow local reads, sent writes to primary
 - Block on write until all replicas are notified
 - Implements sequential consistency

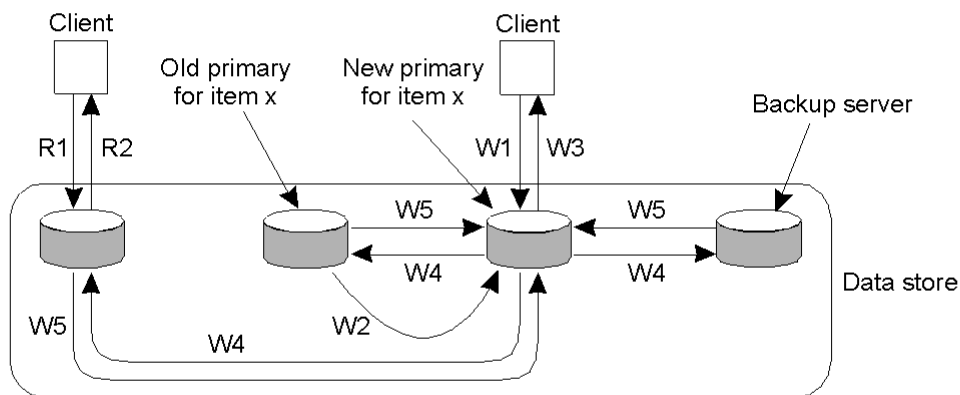
Local-Write Protocols (1)



1. Read or write request
2. Forward request to current server for x
3. Move item x to client's server
4. Return result of operation on client's server

- Primary-based local-write protocol in which a single copy is migrated between processes.
 - Limitation: need to track the primary for each data item

Local-Write Protocols (2)



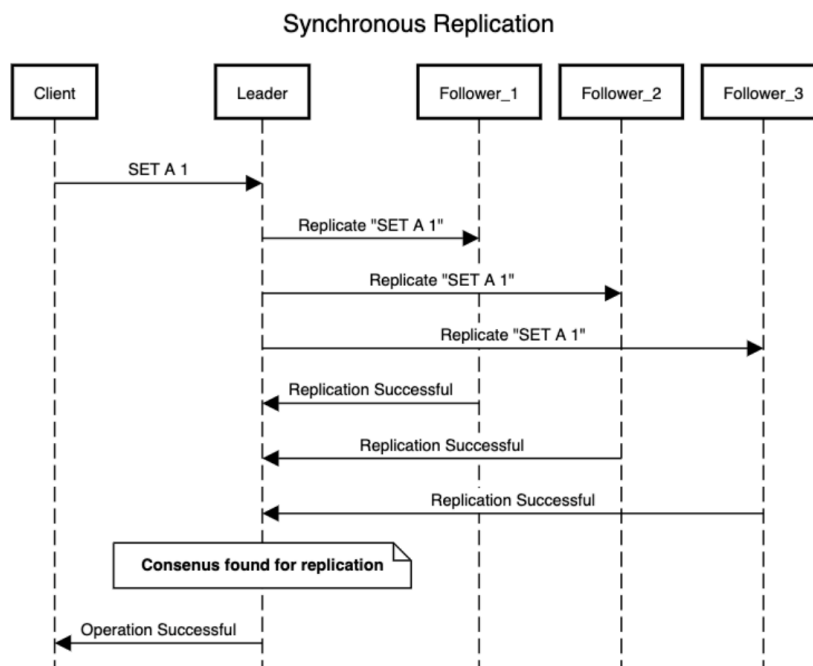
- | | |
|---------------------------------|----------------------|
| W1. Write request | R1. Read request |
| W2. Move item x to new primary | R2. Response to read |
| W3. Acknowledge write completed | |
| W4. Tell backups to update | |
| W5. Acknowledge update | |

- Primary-backup protocol in which the primary migrates to the process wanting to perform an update

Replicated-write Protocols

- Relax the assumption of one primary
 - No primary, any replica is allowed to update
 - Consistency is more complex to achieve
- Synchronous writes to all replicas
- Asynchronous writes to all replicas
-

Synchronous Replication



Asynchronous Replication

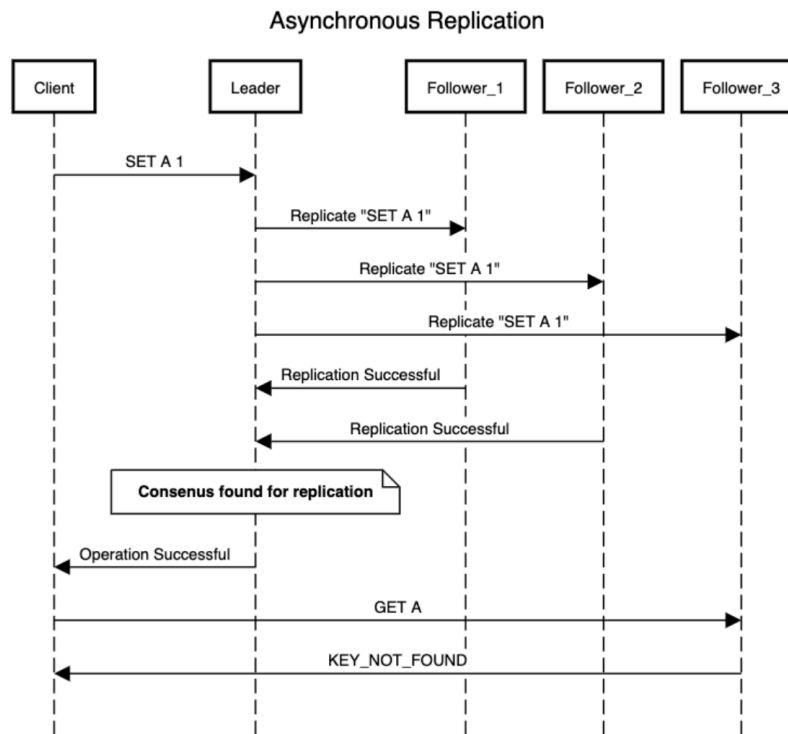
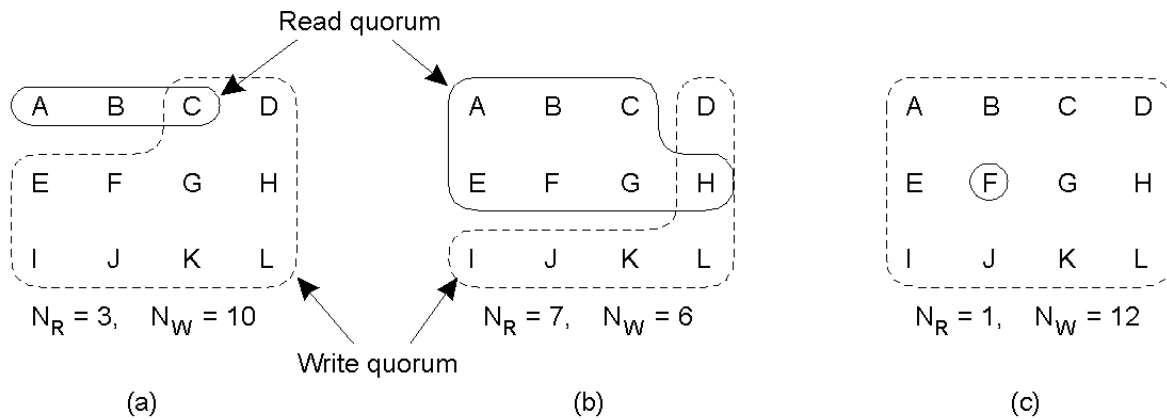


Fig courtesy: V. Upadhyay
Lecture 18, page 9

Replicated-write Protocols

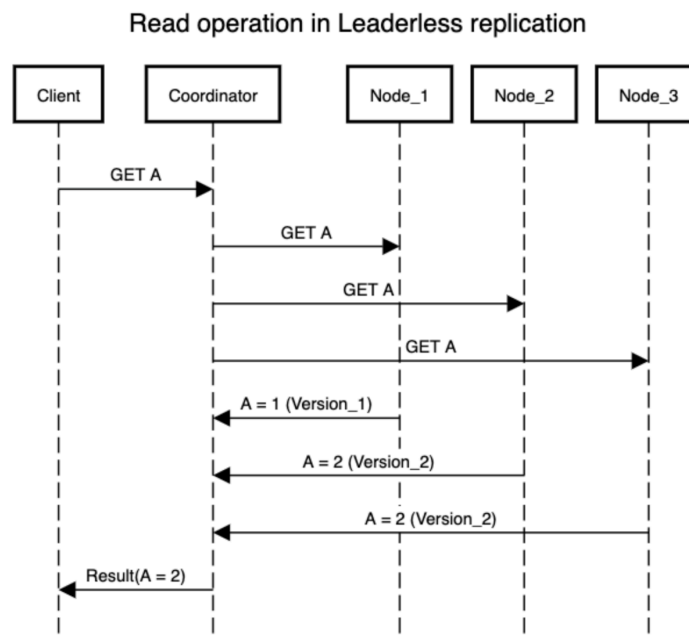
- Relax the assumption of one primary (“leaderless”)
 - No primary, any replica is allowed to update
 - Consistency is more complex to achieve
- Quorum-based protocols
 - Use voting to request/acquire permissions from replicas
 - Consider a file replicated on N servers
 - $N_R + N_W > N$ $N_W > N/2$
 - Update: contact N_W servers and get them to agree to do update (associate version number with file)
 - Read: contact N_R and obtain version number
 - If all servers agree on a version number, read

Gifford's Quorum-Based Protocol

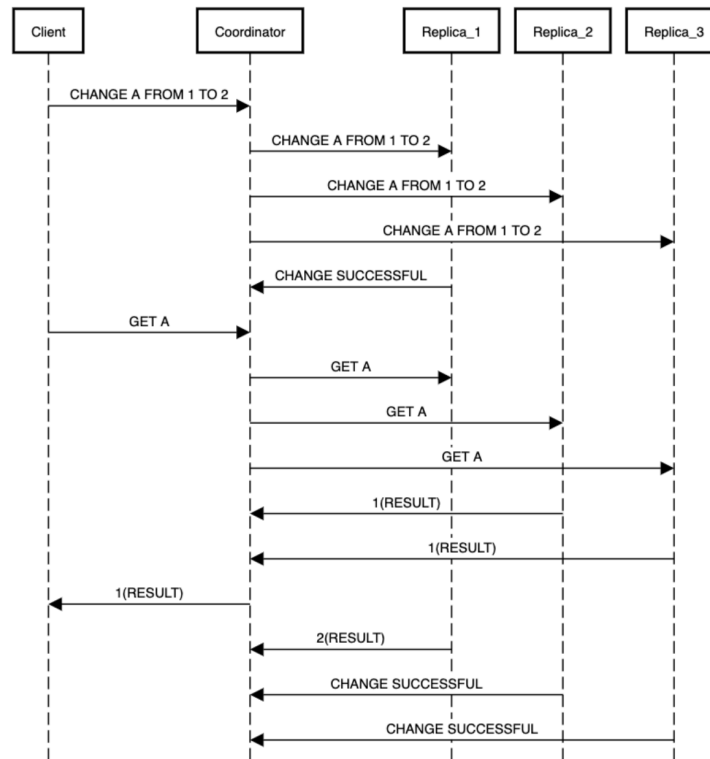


- Three examples of the voting algorithm:
 - a) A correct choice of read and write set
 - b) A choice that may lead to write-write conflicts
 - c) A correct choice, known as ROWA (read one, write all)

Quorums In Action



Quorums in Action



UMassAmherst

CS677: Distributed and Operating Systems

Fig courtesy: V. Upadhyay
Lecture 18, page 13

Replica Management

- Replica server placement
 - Web: geographically skewed request patterns
 - Where to place a proxy?
 - K-clusters algorithm
- Permanent replicas versus temporary
 - Mirroring: all replicas mirror the same content
 - Proxy server: on demand replication
- Server-initiated versus client-initiated

UMassAmherst

CS677: Distributed and Operating Systems

Lecture 18, page 14

Final Thoughts

- Replication and caching improve performance in distributed systems
- Consistency of replicated data is crucial
- Many consistency semantics (models) possible
 - Need to pick appropriate model depending on the application
 - Example: web caching: weak consistency is OK since humans are tolerant to stale information (can reload browser)
 - Implementation overheads and complexity grows if stronger guarantees are desired

Fault Tolerance

- Single machine systems
 - Failures are all or nothing
 - OS crash, disk failures
- Distributed systems: multiple independent nodes
 - Partial failures are also possible (some nodes fail)
- *Question:* Can we automatically recover from partial failures?
 - Important issue since probability of failure grows with number of independent components (nodes) in the systems
 - $\text{Prob}(\text{failure}) = \text{Prob}(\text{Any one component fails}) = 1 - P(\text{no failure})$

A Perspective

- Computing systems are not very reliable
 - OS crashes frequently (Windows), buggy software, unreliable hardware, software/hardware incompatibilities
 - Until recently: computer users were “tech savvy”
 - Could depend on users to reboot, troubleshoot problems
 - Growing popularity of Internet/World Wide Web
 - “Novice” users
 - Need to build more reliable/dependable systems
 - Example: what if your TV (or car) broke down every day?
 - Users don’t want to “restart” TV or fix it (by opening it up)
- Need to make computing systems more reliable
 - Important for online banking, e-commerce, online trading, webmail...

Basic Concepts

- Need to build *dependable* systems
- Requirements for dependable systems
 - Availability: system should be available for use at any given time
 - 99.999 % availability (five 9s) => very small down times
 - Reliability: system should run continuously without failure
 - Safety: temporary failures should not result in a catastrophic
 - Example: computing systems controlling an airplane, nuclear reactor
 - Maintainability: a failed system should be easy to repair

Basic Concepts (contd)

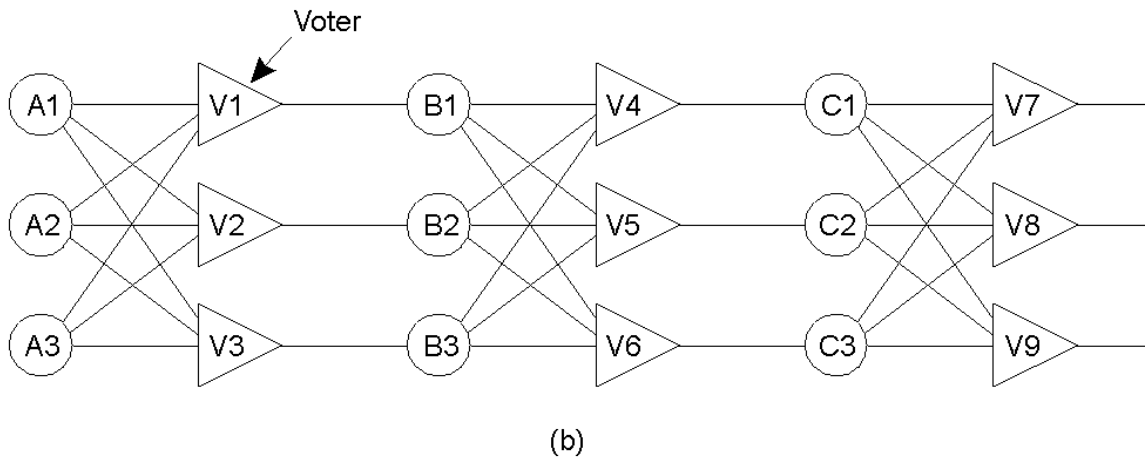
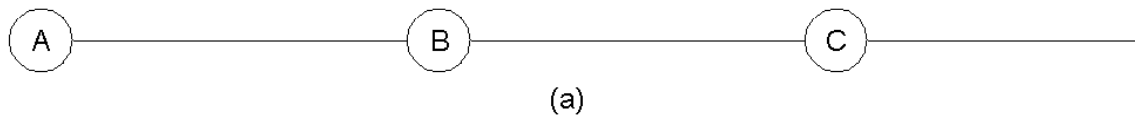
- Fault tolerance: system should provide services despite faults
 - Transient faults
 - Intermittent faults
 - Permanent faults

Failure Models

Type of failure	Description
Crash failure	A server halts, but is working correctly until it halts
Omission failure <i>Receive omission</i> <i>Send omission</i>	A server fails to respond to incoming requests A server fails to receive incoming messages A server fails to send messages
Timing failure	A server's response lies outside the specified time interval
Response failure <i>Value failure</i> <i>State transition failure</i>	The server's response is incorrect The value of the response is wrong The server deviates from the correct flow of control
Arbitrary failure	A server may produce arbitrary responses at arbitrary times

- Different types of failures.

Failure Masking by Redundancy



- Triple modular redundancy.