

Last Class: Fault Tolerance

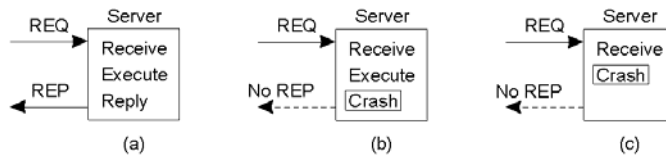
- Basic concepts and failure models
- Failure masking using redundancy
- Agreement in presence of faults
 - Two army problem
 - Byzantine generals problem

Today: More on Fault Tolerance

- Reliable communication
 - One-one communication
 - One-many communication
- Distributed commit
 - Two phase commit
 - Three phase commit
- Failure recovery
 - Checkpointing
 - Message logging

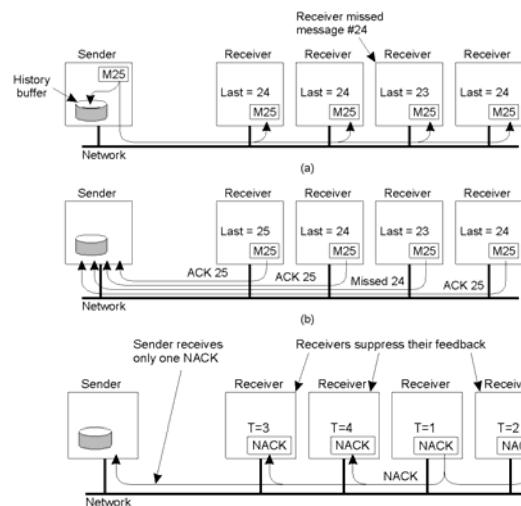
Reliable One-One Communication

- Issues were discussed in Lecture 3
 - Use reliable transport protocols (TCP) or handle at the application layer
- RPC semantics in the presence of failures
- Possibilities
 - Client unable to locate server
 - Lost request messages
 - Server crashes after receiving request
 - Lost reply messages
 - Client crashes after sending request



Reliable One-Many Communication

- Reliable multicast
 - Lost messages => need to retransmit
- Possibilities
 - ACK-based schemes
 - Sender can become bottleneck
 - NACK-based schemes



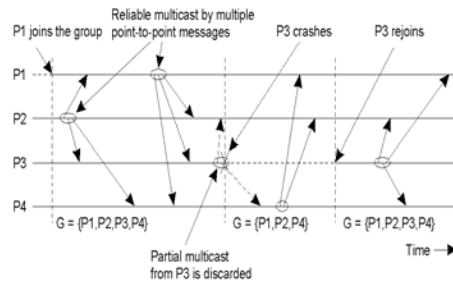
Atomic Multicast

- Atomic multicast: a guarantee that all process received the message or none at all
 - Replicated database example

- Problem: how to handle process crashes?

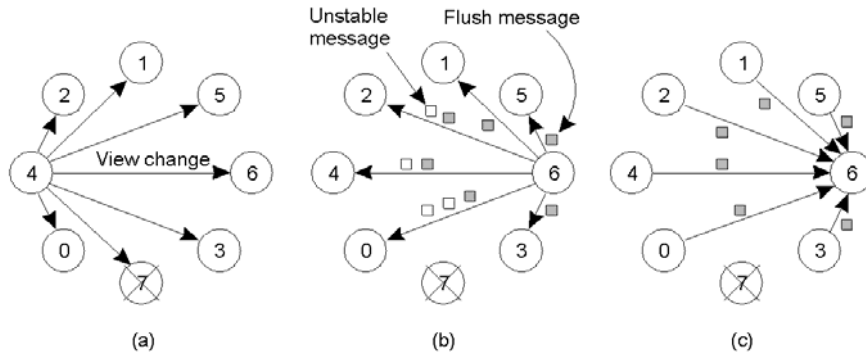
- Solution: *group view*

- Each message is uniquely associated with a group of processes
 - View of the process group when message was sent
 - All processes in the group should have the same view (and agree on it)



Virtually Synchronous Multicast

Implementing Virtual Synchrony in Isis



- Process 4 notices that process 7 has crashed, sends a view change
- Process 6 sends out all its unstable messages, followed by a flush message
- Process 6 installs the new view when it has received a flush message from everyone else

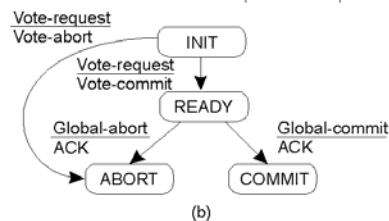
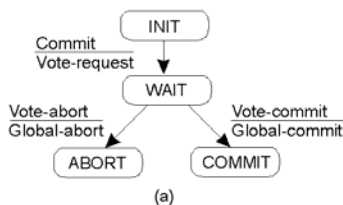
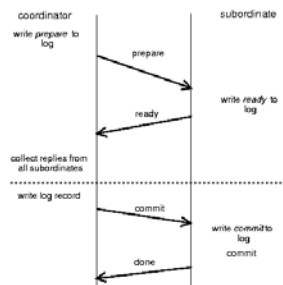
Distributed Commit

- Atomic multicast example of a more general problem
 - All processes in a group perform an operation or not at all
 - Examples:
 - Reliable multicast: Operation = delivery of a message
 - Distributed transaction: Operation = commit transaction
- Problem of distributed commit
 - All or nothing operations in a group of processes
- Possible approaches
 - Two phase commit (2PC) [Gray 1978]
 - Three phase commit



Two Phase Commit

- Coordinator process coordinates the operation
- Involves two phases
 - Voting phase: processes vote on whether to commit
 - Decision phase: actually commit or abort



Implementing Two-Phase Commit

actions by coordinator:

```
while START_2PC to local log;
multicast VOTE_REQUEST to all participants;
while not all votes have been collected {
  wait for any incoming vote;
  if timeout {
    while GLOBAL_ABORT to local log;
    multicast GLOBAL_ABORT to all participants;
    exit;
  }
  record vote;
}
if all participants sent VOTE_COMMIT and coordinator votes COMMIT{
  write GLOBAL_COMMIT to local log;
  multicast GLOBAL_COMMIT to all participants;
} else {
  write GLOBAL_ABORT to local log;
  multicast GLOBAL_ABORT to all participants;
}
```

- Outline of the steps taken by the coordinator in a two phase commit protocol



Implementing 2PC

actions by participant:

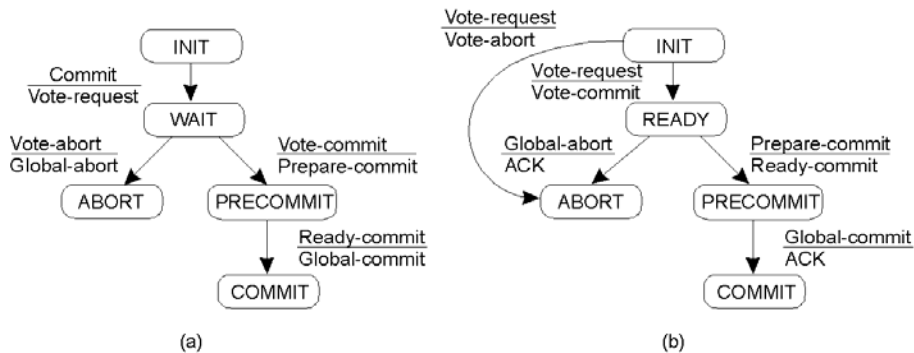
```
write INIT to local log;
wait for VOTE_REQUEST from coordinator;
if timeout {
  write VOTE_ABORT to local log;
  exit;
}
if participant votes COMMIT {
  write VOTE_COMMIT to local log;
  send VOTE_COMMIT to coordinator;
  wait for DECISION from coordinator;
  if timeout {
    multicast DECISION_REQUEST to other participants;
    wait until DECISION is received; /* remain blocked */
    write DECISION to local log;
  }
  if DECISION == GLOBAL_COMMIT
    write GLOBAL_COMMIT to local log;
  else if DECISION == GLOBAL_ABORT
    write GLOBAL_ABORT to local log;
} else {
  write VOTE_ABORT to local log;
  send VOTE_ABORT to coordinator;
}
```

actions for handling decision requests:

```
/*executed by separate thread */
while true {
  wait until any incoming DECISION_REQUEST
  is received; /* remain blocked */
  read most recently recorded STATE from the
  local log;
  if STATE == GLOBAL_COMMIT
    send GLOBAL_COMMIT to requesting
    participant;
  else if STATE == INIT or STATE ==
    GLOBAL_ABORT
    send GLOBAL_ABORT to requesting
    participant;
  else
    skip; /* participant remains blocked */
}
```



Three-Phase Commit



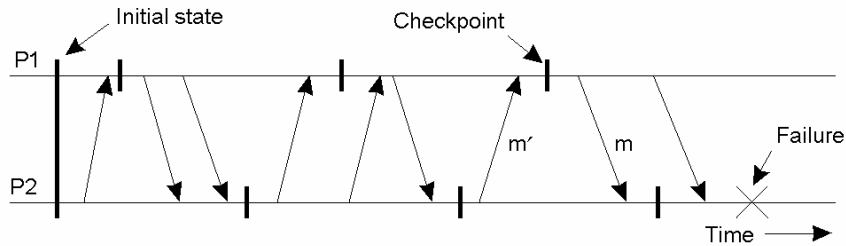
Two phase commit: problem if coordinator crashes (processes block)

Three phase commit: variant of 2PC that avoids blocking

Recovery

- Techniques thus far allow failure handling
- Recovery: operations that must be performed after a failure to recover to a correct state
- Techniques:
 - Checkpointing:
 - Periodically checkpoint state
 - Upon a crash roll back to a previous checkpoint with a *consistent state*

Independent Checkpointing



- Each processes periodically checkpoints independently of other processes
- Upon a failure, work backwards to locate a consistent cut
- Problem: if most recent checkpoints form inconsistent cut, will need to keep rolling back until a consistent cut is found
- Cascading rollbacks can lead to a domino effect.

Coordinated Checkpointing

- Take a distributed snapshot [discussed in Lec 11]
- Upon a failure, roll back to the latest snapshot
 - All process restart from the latest snapshot

Message Logging

- Checkpointing is expensive
 - All processes restart from previous consistent cut
 - Taking a snapshot is expensive
 - Infrequent snapshots => all computations after previous snapshot will need to be redone [wasteful]
- Combine checkpointing (expensive) with message logging (cheap)
 - Take infrequent checkpoints
 - Log all messages between checkpoints to local stable storage
 - To recover: simply replay messages from previous checkpoint
 - Avoids recomputations from previous checkpoint